Parallel Block-Delayed Sequences





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PPoPP 2022

Programming with Collections

- sequences, sets, dictionaries, etc.
- map, reduce, filter, scan, etc.
- classic and popular
 - before I was born: APL, SETL, Backus's FP, CM-Lisp, C*, NESL, ...
 - NumPy (Python), MATLAB, Julia, LINQ (C#), ...
- naturally parallel

 - functional style avoids race conditions
- succinct, easy-to-understand algorithms
 - abstract over algorithm design (e.g. divide-and-conquer ==> reduce)
 - higher-order functions

- nowadays, ubiquitous: MapReduce, Spark, Java Streams, Repa (Haskell), Futhark,

- in terms of performance (bulk operations) and semantics (no concurrency by default)

Efficiency?

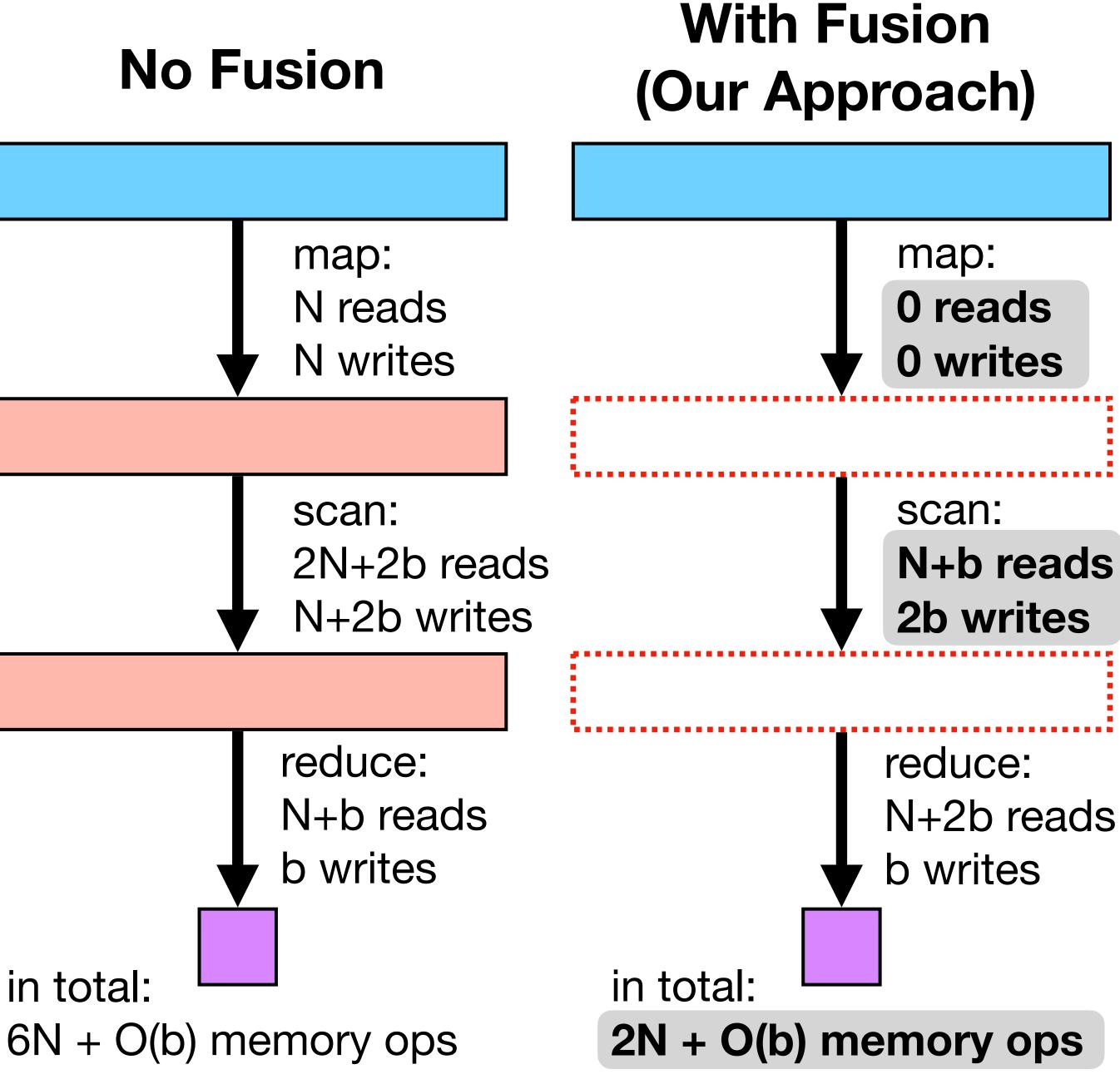
- standard problem:

excess writes for temporary (intermediate) results

- solution: fusion

- optimize across operations
- delay computation until results are needed
- for example: map(f,map(g,S)) fuse map(fog, S)

in total:

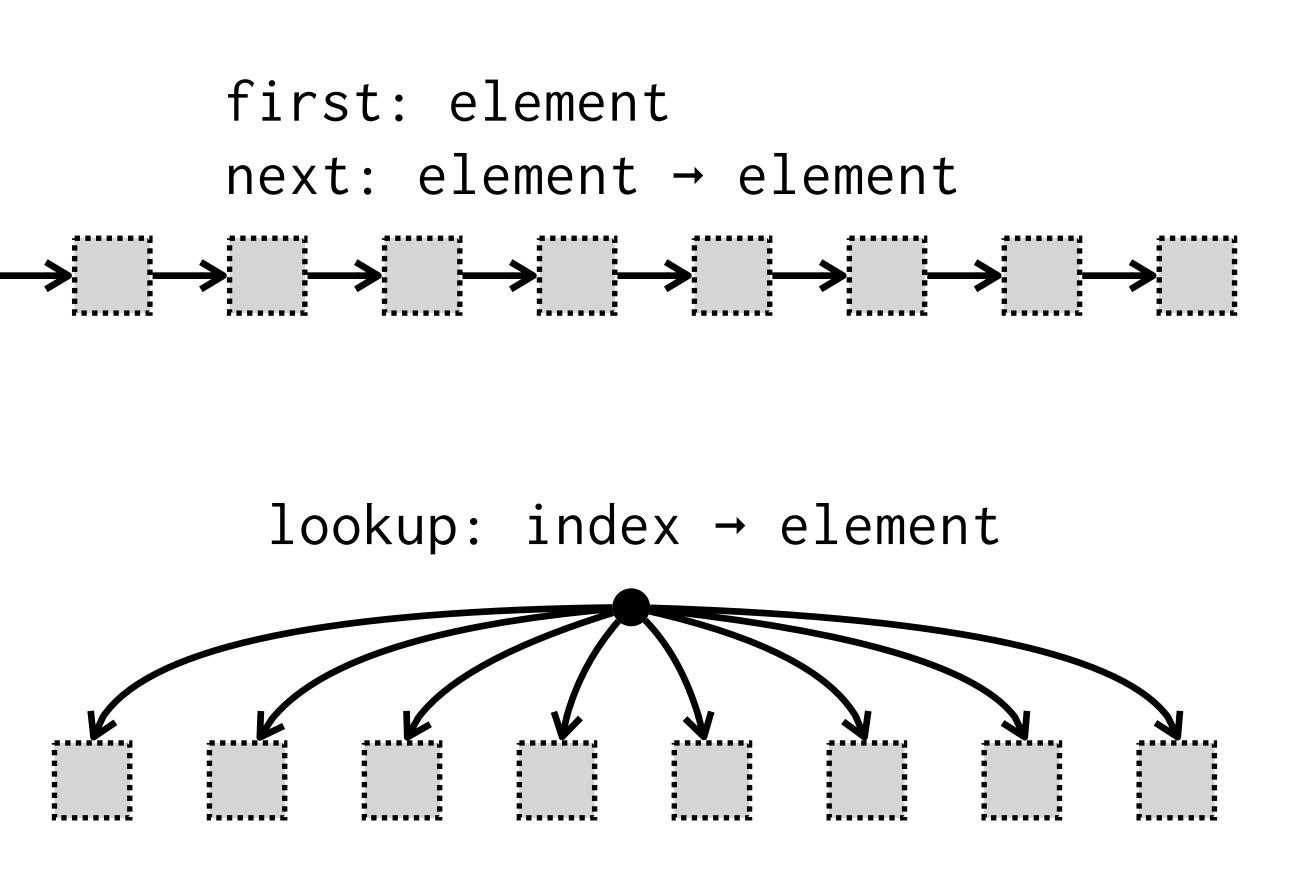


Fusion Breakdown

- Stream fusion

- naturally sequential
- e.g. lazy lists, Java streams, C++20 ranges/views, Rust iterators, ...
- Index fusion
 - naturally parallel
 - elements have to independent
 - good for map/zip/reduce fusion
 - e.g. Repa [1]

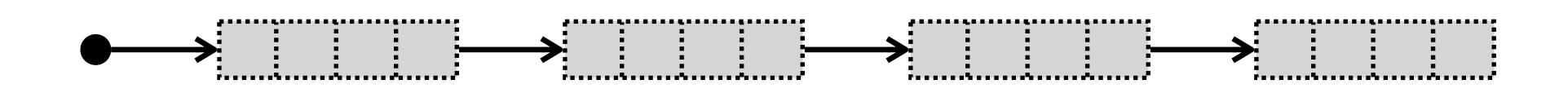
[1] Regular, Shape-polymorphic, Parallel Arrays in Haskell. Gabriele Keller, Manuel M. T. Chakravarty, Roman Leshchinskiy, Simon Peyton Jones, and Ben Lippmeier. ICFP 2010.





Fusion Breakdown (cont.)

- related work: **stream-of-blocks** [1,2]
 - parallelism within a block
 - stream fusion across blocks
 - well-suited for fine-grained SIMD
 - e.g. vectorized, GPU (can choose block size to match vectorization)
 - does not perform well on multicore
 - requires massive blocks to amortize synchronization



[1] Futhark: Purely Functional GPU Programming with Nested Parallelism and In-Place Array Updates. Troels Henriksen, Niels G. W. Serup, Martin Elsman, Fritz Henglein, and Cosmin E. Oancea. PLDI 2017. [2] Exploiting Vector Instructions with Generalized Stream Fusion. Geoffrey Mainland, Roman Leshchinskiy, and Simon Peyton Jones. CACM 2017.

Challenges

- portability

- does it require integration with compiler?
- does it rely on language-specific features?

- fusion across wide set of parallel operations

- in addition to normal map/zip/reduce fusion, can it do:
 - scan (parallel prefix sums)?
 - filter ?
 - flatten (seq<seq<T>> \rightarrow seq<T>)?

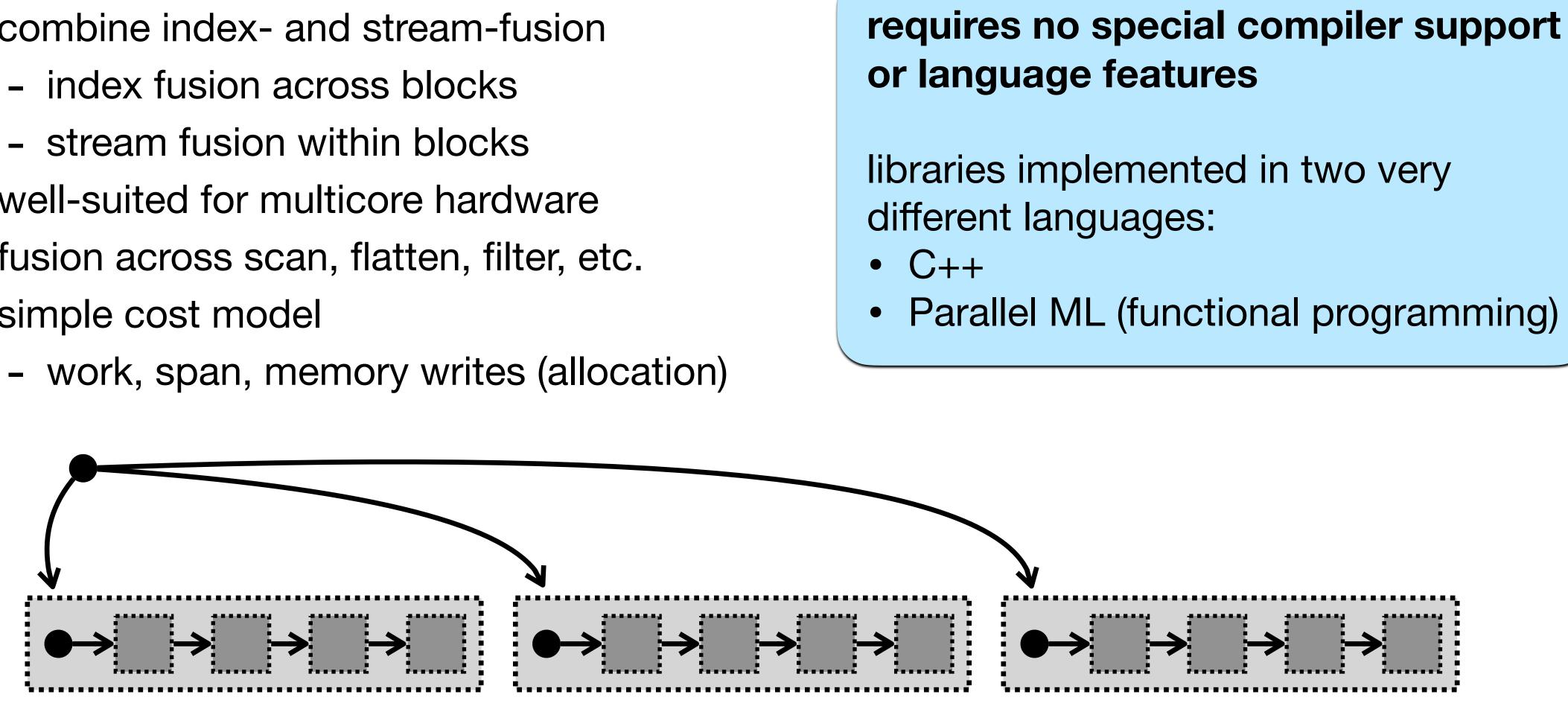
reasoning about performance

- where does fusion happen?
- how many memory writes?

Block-Delayed Sequences

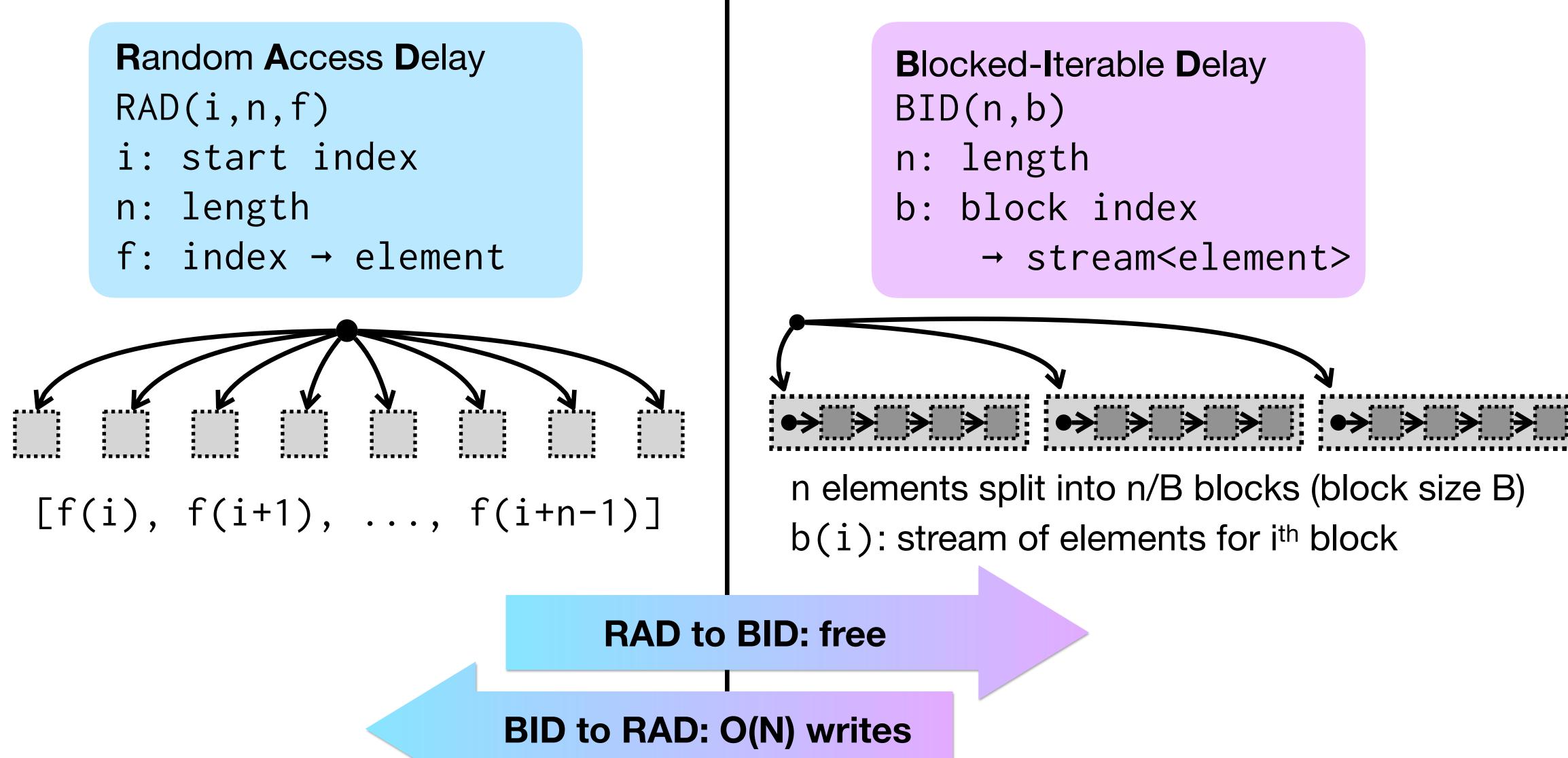
our approach: "blocks of streams"

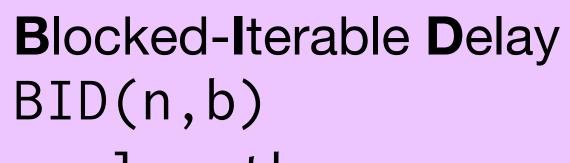
- combine index- and stream-fusion
 - index fusion across blocks
 - stream fusion within blocks
- well-suited for multicore hardware
- fusion across scan, flatten, filter, etc.
- simple cost model



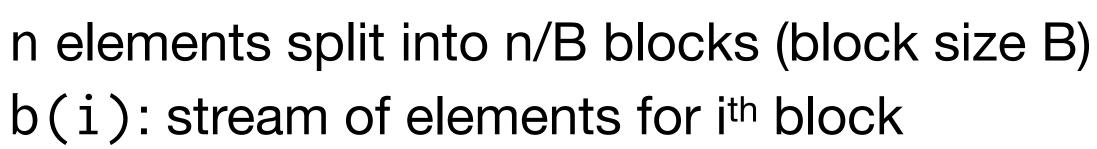


Block-Delayed Sequences



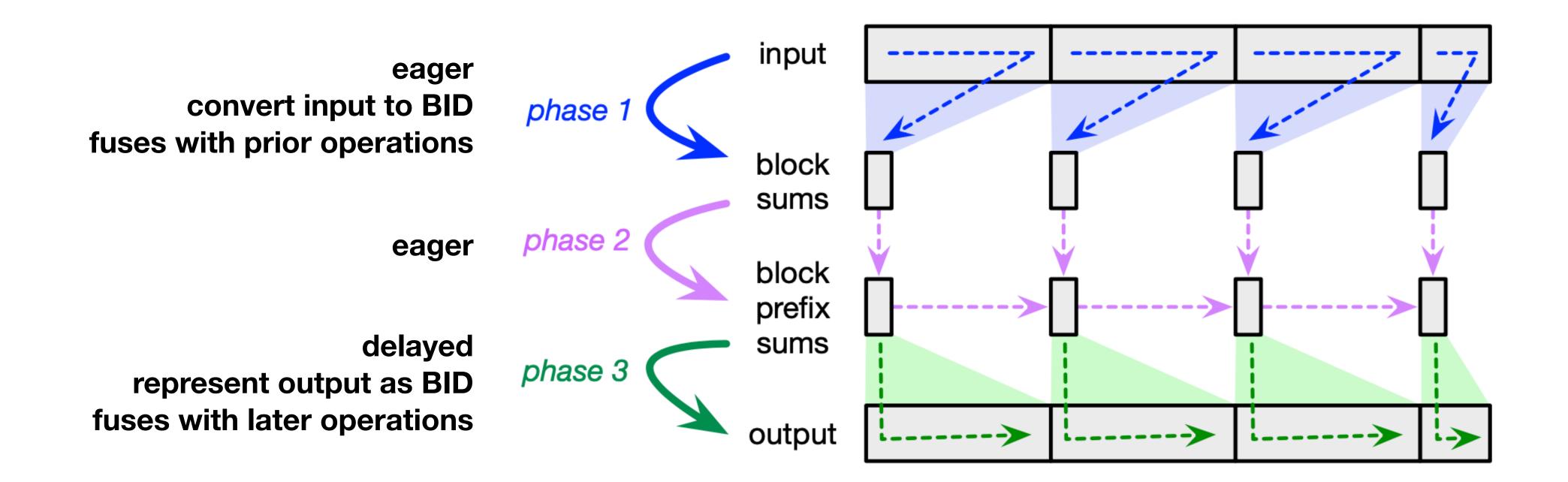


- n: length
- b: block index
 - → stream<element>





Block-Delayed Sequences: Scan



Block-Delayed Sequences: Flatten (Filter is similar)

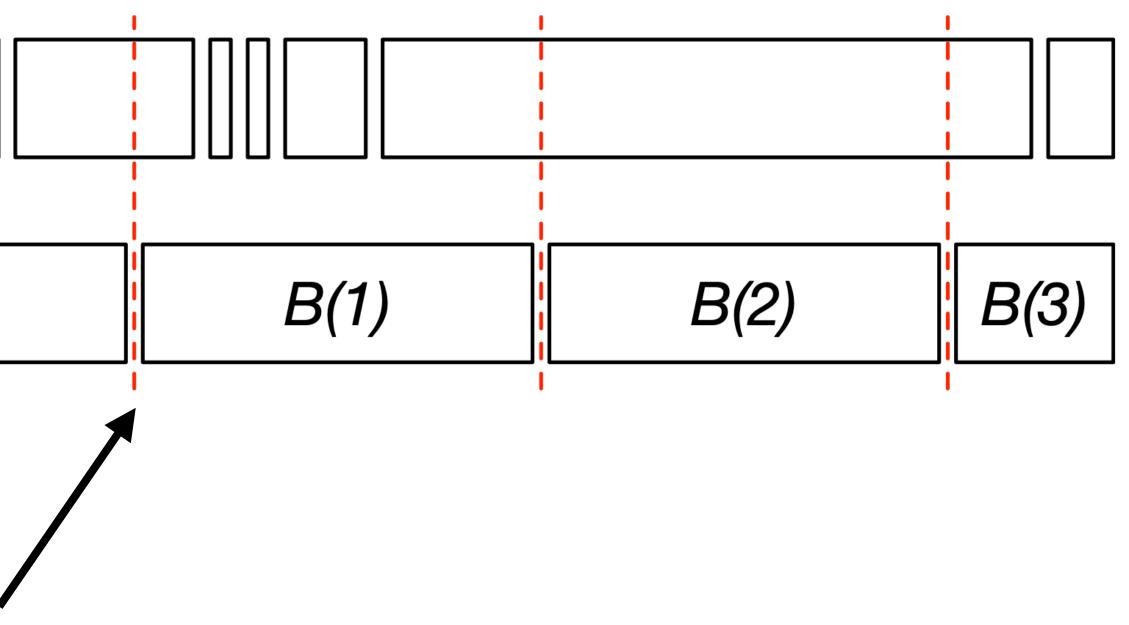
input fuses with previous operations (force outer elements to compute offsets; inner remain delayed)

B(0)

output represented as **BID** fuses with later operations

block stream:

2. to compute next, advance pointer in subsequence or move to next subsequence



1. binary search (on length offsets) to find start

Example (BFS) and Cost Analysis

function nextFrontier(F): E = flatten(map(outEdges, F)) F' = filter(tryVisit, E) return F'

• • •

function outEdges(u):
 return map(fn(v) => (u,v), neighbors(u))

// visit v from edge (u,v); return v if success
function tryVisit(u,v):

Cost analysis (single round of BFS): linear work polylog span only O(|F| + |F'| + |E|/B) memory writes

Implementations

- C++
- streams as stateful iterators
 - templated to specialize for a particular type
- overloading used to dispatch on sequence representation (BID vs RAD)
- updated PBBS benchmarks

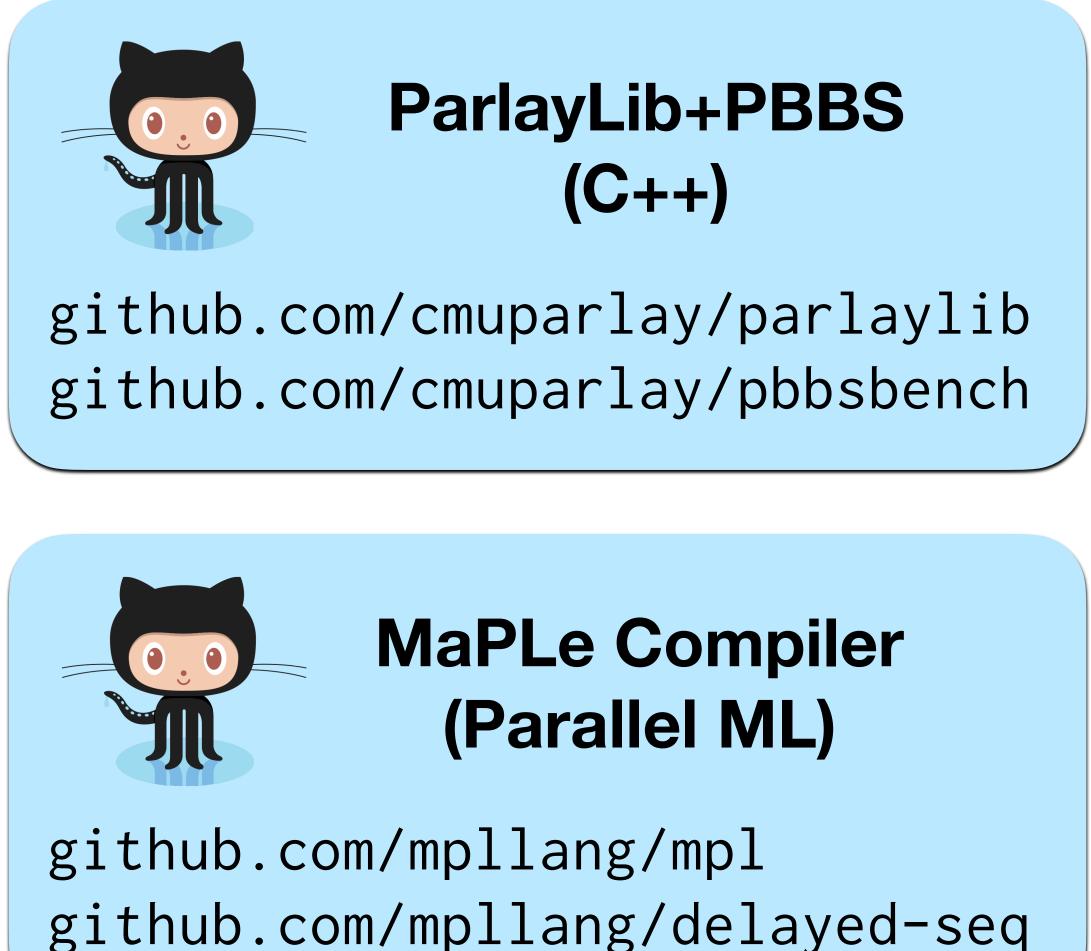
Parallel ML (MPL)

- streams as stateful functions of type unit \rightarrow unit \rightarrow 'a. For example:

S = makeStream()

x0 = S(); x1 = S(); ...

- algebraic datatype for sequences, one variant per representation
 - standard compiler optimizations inline and specialize





Experimental Evaluation

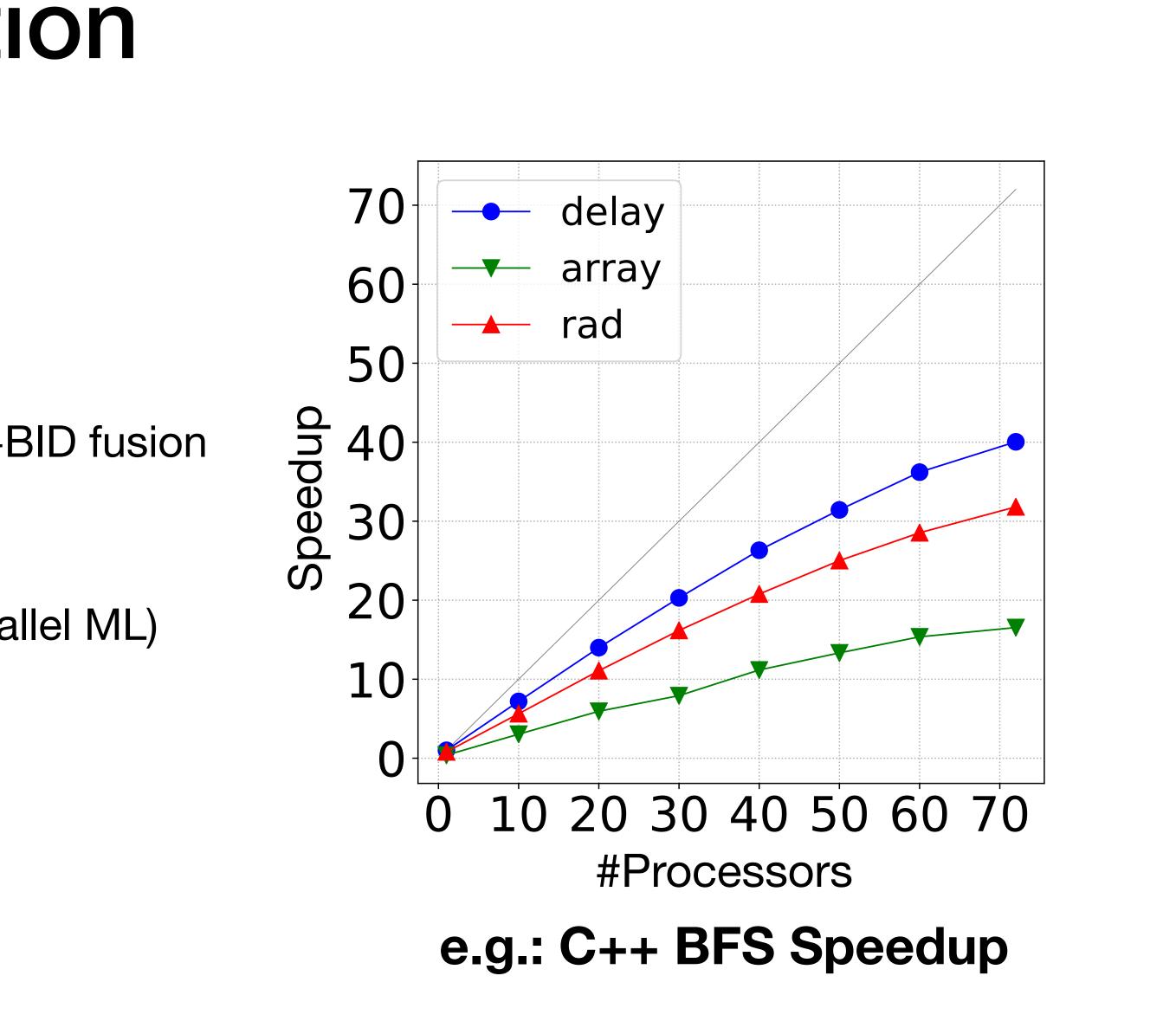
Three libraries compared:

- array: no fusion, arrays only
- rad: extends array with RAD fusion
- delay (full library): extends array with RAD+BID fusion

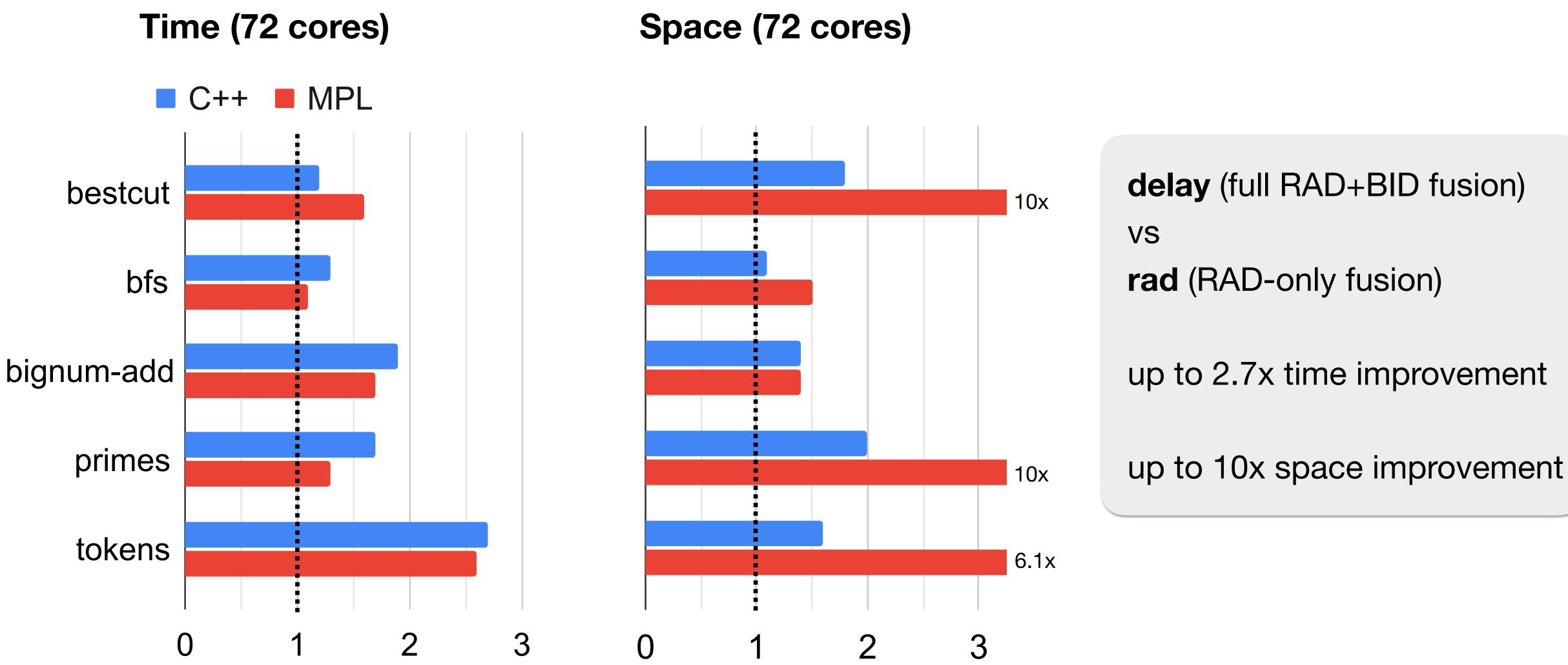
Six libraries in total (Everything implemented in both C++ and Parallel ML)

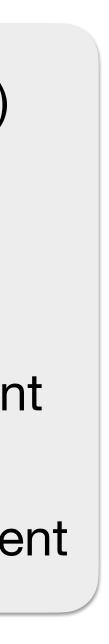
13 PBBS benchmarks

- 5 benefit from BID+RAD fusion
- 8 benefit from only RAD fusion

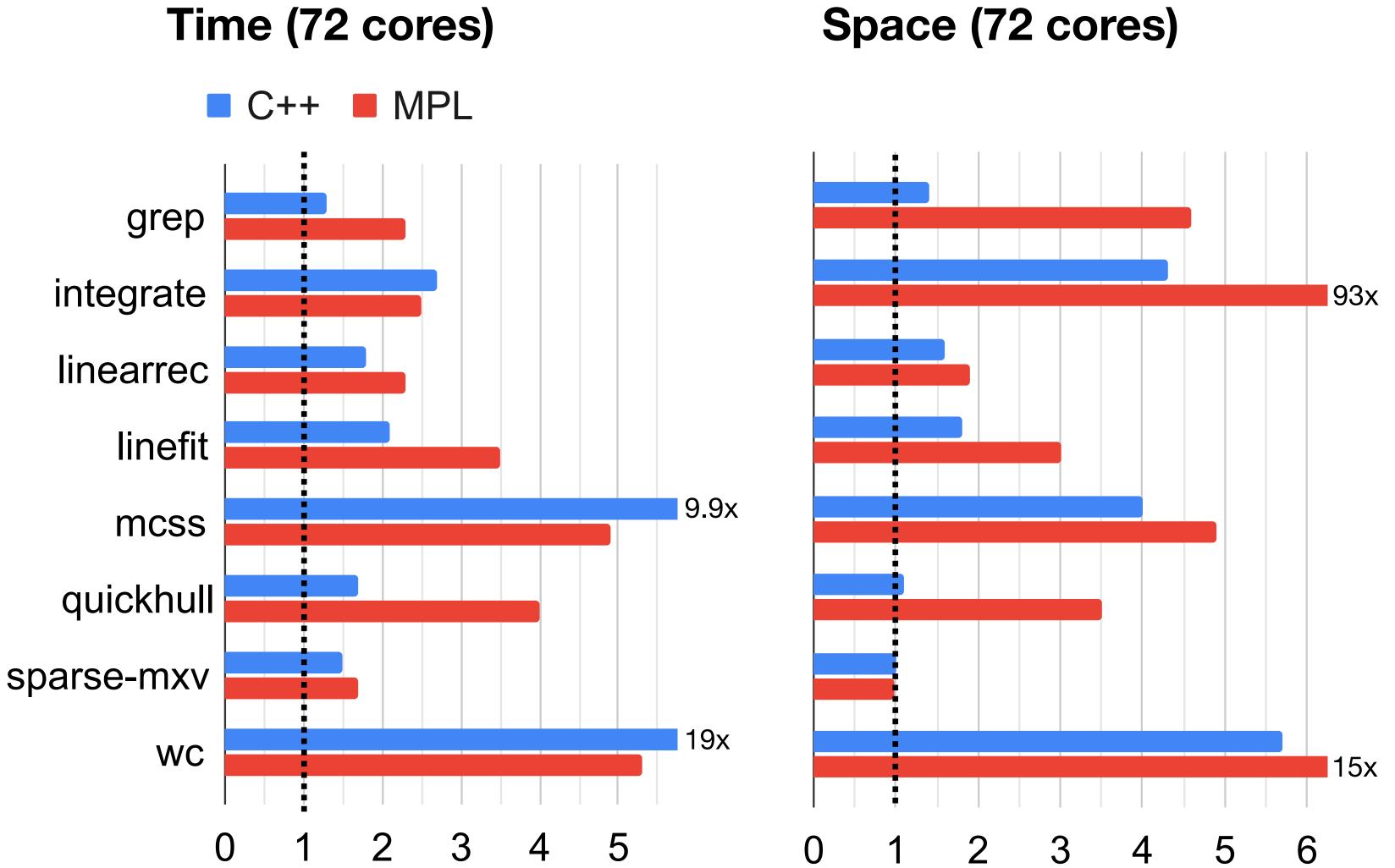


BID Fusion Improvement





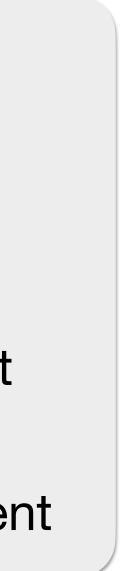
RAD Fusion Improvement



delay (full RAD+BID fusion) VS array (no fusion)

up to 19x time improvement

up to 93x space improvement



Summary

parallel block-delayed sequences

- new "blocks of streams" representation (BID)
- supports fusion across all common operations (including scan, flatten, filter, etc.)
- simple to implement
- portable across multiple languages
 - implementations in both C++ and Parallel ML
- significant improvements in both space and time

future work

- extend to many-core and distributed computing

ParlayLib+PBBS (C++)

github.com/cmuparlay/parlaylib github.com/cmuparlay/pbbsbench



